Second Generation of Eurocode 8

Use of anti-seismic devices

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STRUCTURES EQUIPPED WITH ANTI-SEISMI DEVICES – GENERAL ASPECTS EN1998 1-1



Anti-seismic devices

 Rigid Connection Device (shock transmission units, guide and restraint bearings, mechanical fuses)

ENERGY DISSIPATION DEVICES

• **Displacement-Dependent Device** (friction, hysteretic...)

 Velocity-Dependent Device (fluid viscous F=Cv1αlve, viscoelastic F=Kd+Cv...)

Seismic Isolator (elastomeric isolators, sliders...) Section 6.8 of EN1998-1-1 covers the GENERAL ASPECTS for all type of antiseismic devices and structures (buildings, bridges, tanks...)

AUXILIARY ELEMENS OF + ENERGY + MAIN DISSIPATION SYSTEM AMAIN STRUCTURE = STRUCTURE EQUIPPED WITH ENERGY DISSIPATION SYSTEMS

ENERGY SUPERSTRUCTURE BASE + DISSIPATION + AND = ISOLATED DEVICES SUBSTRUCTURE STRUCTURE

BASIS OF DESIGN

- Increased reliability is required to **anti-seismic devices** and their **connections** (i.e. displacements, velocities increased by γ_X).
- Auxiliary elements of the energy dissipation system should remain elastic.
- The isolation system should present re-centring capability in both horizontal directions
- The isolation system should provide sufficient lateral restraint at the isolation interface to satisfy limitation of displacements/deformations.

MODELLING

• Multiple analysis should be conducted to bound the effects of varying properties of anti-seismic devices.

TRUCTURES EQUIPPED WITH ANTI-SEISMIC DEVICES – GENERAL ASPECTS EN1998 1-1







Fundamental-mode equivalent linear response-spectrum analysis*

STRUCTURES • WITH FULL ISOLATION •

- Superstructure and substructure in case of buildings, or the deck in case of bridges, are assumed rigid (rigid masses)
- The higher modes of superstructure/substructure are neglected
- The structure is assumed to respond predominantly as a SDOF system in each horizontal direction, but the torsional effects about a vertical axis are accounted for.
- The isolation system is modelled as an equivalent linear SDOF system with *Kleff* and $\xi leff = 1/2\pi [\Sigma^{\uparrow \parallel \parallel} ElD,i / Kleff dlEd12]$. Here, *Kleff* is obtained from the secant stiffness *kleff,i* of isolators in case of buildings, and also from the displacement stiffness of piers and translation/rotational stiffness of foundations in case of bridges. *ElD,i* is the dissipated energy of each anti-seismic devices (isolator and EDDs). *Kleff* and $\xi leff$ depend on design displacement d_{bd} (iterations required).

*≈ simplified linear analysis in current EN1998-1



Multi-mode equivalent linear response-spectrum analysis*

- Superstructure/substructure represented by flexible elastic 3D model
 - The higher modes of superstructure/substructure considered
 - The response in the first modes involving deformations of the isolation system (i.e. affected by anti-seismic devices) is obtained representing the structure as an equivalent SDOF system with an effective period *Tleff*, and with an effective damping *\xi leff* calculated with the *ELD,i* dissipated by each anti-seismic device.
 - The response in the higher modes not involving deformations of the isolation system (i.e. not affected by anti-seismic devices) are obtained with the ξ of a non-isolated structure.

*≈ full modal analysis in current EN1998-1

STRUCTURES

WITH FULL

ISOLATION

• The response in each mode through response spectrum analysis.



STRUCTURES WITH FULL OR PARTIAL ISOLATION

STRUCTURES WITH ENERGY DISSIPATION SYSTEMS

Response-history analysis

- Constitutive relationships of anti-seismic devices must adequately reproduce their behaviour in the range of deformations and velocities of the design seismic situation
- In structures on near-fault sites, each pair of horizontal input motion component should be rotated to the fault-normal and fault-parallel directions of the causative fault and applied to the model in such orientation
- The inherent damping ratio of the structure (i.e. before yielding) $\leq 3\%$



BUILDINGS WITH BASE ISOLATION- Chapter 8 of EN1998-1-2

- Chapter 8 provides additional (few) provisions for buildings with **full** base isolation
- Additional conditions are set for applying the fundamental-mode equivalent linear response-spectrum analysis in buildings, e.g.

 $3T\downarrow f \leq T\downarrow eff \leq 3$; $K\downarrow V/K\downarrow eff \geq 150$; $T\downarrow V = 2\pi\sqrt{M/K\downarrow V} \leq 0.1s$

• Seismic action effects on superstructure and substructure are calculated with q=1.5.



BRIDGES WITH ISOLATION- Chapter 8 of EN1998-2

- Chapter 8 provides additional (few) provisions for bridges with full or partial isolation
- The superstructure (deck) should remain always elastic
- In case of full isolation, the substructure should be designed as non-dissipative (DC1; global and local ductility conditions neglected). Exception: for heavy piers in moderate or high seismicity regions DC2 is required.



BUILDINGS WITH ENERGY DISSIPATION SYSTEMS - Chapter 9 of EN1998-1-2

Two types of energy dissipation devices are considered:

> Displacement-Dependent Devices with response controlled <u>only</u> by displacements

(a) devices with rigid-plastic behaviour (e.g. friction dampers) - / / /-

(b) multilinear hysteresis (e.g. metallic dampers) -

> Velocity-Dependent Devices with response influenced by velocity





BASIS OF DESIGN

A building with energy dissipation systems is composed of two systems in parallel:

- Main structural system = primary + secondary structural elements Primary role: sustain gravity loading when subjected to lateral displacements Secondary (optional) role: contribute to energy dissipation through plastic strains
- Energy dissipation system = energy dissipation devices (EDD) + auxiliary elements Primary role: dissipate most of the energy input by the earthquake Secondary (compulsory) role: transfer the forces from EDDs to main structural system





MAIN REQUIREMENTS / VERIFICATIONS

Main structural system:

The energy that the primary seismic \geq members of the main structural system at the k-th storey **can** dissipate before reaching the SD limit state

The maximum energy dissipation **demand** on the primary seismic members of the main structural system at the k-th storey under the design seismic action.

Energy dissipation system:

The energy that the dampers at the k- \geq th storey **can** dissipate before one of them reaches the SD limit state

The maximum energy dissipation **demand** on the dampers at the k-th storey under the reference seismic action BUILDINGS WITH ENERGY DISSIPATION SYSTEMS Chapter 9 EN1998-1-2



These main verifications are done using TWO DIFFERENT ANALYSIS METHODS:

BUILDINGS WITH VELOCITY-DEPENDENT EDDs

- with floor diafragms that are rigid in their plane
- with ≥ 2 EDDs in each direction and each story arranged to provide torsional sittfness/resistance
- same type of EDD, αlve , $\eta loss$ in all stories



NON-LINEAR RESPONSE SPECTRUM ANALYSIS

BUILDINGS WITH DISPLACEMENT-DEPENDENT EDDs

- with floor diafragms that are rigid in their plane
- with ≥2 EDDs in each direcction and each story arranged to provide torsional sitffness/resistance



ENERGY-BALANCE BASED ANALYSIS



COMMON ASPECTS OF BOTH ANALYSIS METHODS:

- The overall system (main structure and energy dissipation devices) is assumed to dissipate energy through plastic deformations only in the first mode (i.e. the vibration mode with largest effective modal mass in the direction under consideration).
- In the higher modes, the overall system is assumed to remain elastic and the response is obtained through conventional response spectrum analysis.

BUILDINGS WITH ENERGY DISSIPATION SYSTEMS Chapter 9 EN1998-1-2



NON LINEAR RESPONSE SPECTRUM ANALYSIS FOR BUILDINGS WITH VELOCITY-DEPENDENT EDDS



- > Combines non-linear static analysis and response spectrum analysis
- > Largely based on the capacity spectrum method (Freeman, 1975)
- > Response in 1st mode is obtained idealizing the overall structure with an equivalent SDOF system with effective stiffness T_{eff1} and effective **viscous** damping ratio $\xi \downarrow eff1$.
- This method is appropriate for structures with velocity-dependent EDDs since their main source of energy dissipation is of the viscous type (i.e. of the same nature as the effective viscous damping used to represent the EDDs).
- This method is questionable for structures with displacement-dependent EDDs since their main source of energy dissipation is of the hysteretic type and there is no physical principle that justifies the existence of a stable relationship between the hysteretic energy dissipation of the maximum excursion and equivalent viscous damping, particularly for highly inelastic systems (Fajfar, 1999; Krawinkler, 1995).



MAIN VERIFICATION of the Main Structural System

The energy that the primary seismic \geq members at the k-th storey **can** dissipate before reaching the SD limit state

The maximum energy dissipation **demand** on the primary seismic members at the k-th storey under the design seismic action.

Indirect verification:

- 1. The main structural system is classified as DC1 or DC2 or DC3 depending on the compliance of the conditions in 6.2.7 EN1998 1-1 and **10** to **15** in EN1998 1-2. This determines the maximum allowable q_D
- 2. Calculate the displacement ductility demand dlroof1 is the maximum roof displacement in the first mode in the direction considered;

$$d_{\text{roofy}} = \frac{V_{\text{py,1}} T_{\text{p1}}^2 \Gamma_{\text{p1}}}{4\pi^2 m_{\text{peff1}}}$$

3. Check: $\mu l f \leq q l D$.



dlroof 1 is obtained idealizing the structure with equivalent SDOF system T_{eff1} and *ξleff* 1 1. Obtain the capacity curve of the main structural system – curve (b)

- 2. Adopt a tentative d_{roof1} and obtain the corresponding $\mu \downarrow f$, Teff1 and $\xi \downarrow eff1$.
- 3. Calculate total base shear V_{b1} by summing up the V_{py1} corresponding to d_{roof1} and the base shear sustained by the the elastic part of EDDs (in case of viscoelastic EDDs).

4. Obtain $V_{b1 max} = m_{eff 1} S_e(T_{eff 1}, 5\%) \eta(T_{eff 1}, \xi_{eff 1}) \rightarrow \text{Is } 0.95 V \downarrow b1 max \leq V \downarrow b1 \leq 1.05 V \downarrow b1 max$





MAIN VERIFICATION on the Energy Dissipation Devices (EDDs):

The energy that the dampers at the k- \geq th storey can dissipate before one of them reaches the SD limit state

The maximum energy dissipation demand on the dampers at the k-th storey under the reference seismic action

Direct verification:

the energy dissipation capacity of the energy dissipation devices installed on each storey k in the direction under consideration when any EDD on the same storey attains its SD limit state (evaluated with EN15129)

$$\frac{1}{2}m\left[\frac{T_{s1}}{2\pi}S_{e}(T_{s1}, 5\%)\eta(T_{s1}, \xi_{I})\right]^{2}$$

Assumes the worst case scenario: all the energy input by the earthquake (except that dissipated by inherent damping) concentrates in a single story k.



ADDITIONAL VERIFICATIONS on the Main Structural System and Auxiliary elements of Energy Dissipation System ($E_d \le R_d$)

The design value of seismic action effects E_d are calculated in three stages:

(i) <u>maximum displacement</u> (ii) <u>maximum velocity</u> (iii) <u>maximum acceleration</u>

 $E\downarrow Emax, disp = \blacksquare SRSS@CQC \{E\downarrow Empty disp, vel\} = \blacksquare SRSS@CQC \{E\downarrow Emax, vel, m\}$



BUILDINGS WITH ENERGY DISSIPATION SYSTEMS Chapter 9 EN1998-1-2



ENERGY-BALANCE BASED ANALYSIS for buildings DISPLACEMENT-DEPENDENT EDDs



- The hysteretic energy is NOT represented by an equivalent viscous damping ratio: the problem is addressed directly in terms of hysteretic energy.
- > Based on the conservation of energy (Housner 1956, Akiyama 1985, Fardis, 2018).
- Ideally suited for application to structures employing energy dissipation devices, since for these systems proper energy management is a key to successful design (Soong and Dargush, 1997).
- The designer is concerned not so much with the resistance to lateral forces (forcedbased approach) or with the lateral displacements (displacement-based approach) but with the product of both, that is, with energy.
- The designer directly and explicitly controls and decides how the energy input into the structure from the earthquake is distributed between the Main Structural System and the Energy Dissipation System.
- > Allows a quantitative control of damage.



MAIN VERIFICATION of the Main Structural System

The energy that the primary seismic \geq members at the k-th storey can dissipate before reaching the SD limit state

The maximum energy dissipation demand on the primary seismic members at the k-th storey under the design seismic action

E↓pH,k,SD

E↓pH,k,max

This verification can be made in two alternative ways:

- Direct verification
- Indirect verification



Direct verification

$$E_{\mathrm{H,k}} = \frac{s_{\mathrm{k}}(p_{\mathrm{k}} p_{\mathrm{t,k}})^{-n}}{\sum_{j=1}^{N} s_{j}(p_{j} p_{\mathrm{t,j}})^{-n}} \left[\frac{1}{2} M \left(\frac{T_{\mathrm{s1}}}{2\pi} S_{\mathrm{e}}(T_{\mathrm{s1}}, 5\%) \eta(T_{\mathrm{s1}}, \xi_{1}) \right)^{2} - \sum_{j=1}^{N} \left(\alpha_{j} \overline{m}_{j} M g d_{\mathrm{py,j}}/2 \right) \right] \qquad V_{\mathrm{k}}$$

$$S_{\mathrm{k}} = \left\{ \overline{m}_{\mathrm{k}} + \frac{2T_{1}}{1+3T_{1}} \left(\sqrt{\overline{m}_{\mathrm{k}}} - \overline{m}_{\mathrm{k}}^{2} \right) \right\}^{2} \frac{d_{\mathrm{py,k}}(V_{\mathrm{py,1}}+V_{\mathrm{dy,l}})}{d_{\mathrm{py,1}}(V_{\mathrm{py,k}}+V_{\mathrm{dy,k}})} \left[p_{\mathrm{k}} = \frac{(V_{\mathrm{py,k}}+V_{\mathrm{dy,k}})}{(V_{\mathrm{py,1}}+V_{\mathrm{dy,1}})} \left\{ \overline{m}_{\mathrm{k}} + \frac{2T_{1}}{1+3T_{1}} \left(\sqrt{\overline{m}_{\mathrm{k}}} - \overline{m}_{\mathrm{k}}^{2} \right) \right\}^{-1} \qquad V_{\mathrm{pb,k}} + V_{\mathrm{dy,k}}} \right] \qquad V_{\mathrm{pb,k}} + V_{\mathrm{dy,k}}$$

$$F_{\mathrm{ph,k,max}} = E_{\mathrm{H,k}} \left[\frac{V_{\mathrm{py,k}}(d_{\mathrm{r,k,1}} - d_{\mathrm{py,k}})}{(V_{\mathrm{py,k}}(d_{\mathrm{r,k,1}} - d_{\mathrm{py,k}})} + V_{\mathrm{dy,k}}(d_{\mathrm{r,k,1}} - d_{\mathrm{dy,k}})} \right] \qquad \text{distance between } \sqrt{K \downarrow torsion / center of stiffness K \downarrow lateral}} \qquad O_{\mathrm{dy,k}} d_{\mathrm{b,k}} d_{\mathrm{py,k}} d_{\mathrm{r,k,1}}$$

B-Estimate ElpH,k,SD

A-Estimate *ElpH,k,max*

- $E\downarrow pH,k,SD$ is the plastic strain energy dissipation capacity under cyclic (not monotonic) loading
- *ElpH,k,SD* is determined from the cyclic response of structural members or subassemblies obtained experimentally –EN1998 1-1 clause 7.1.(9). The deformation and strength models of EN 1998 1-1 clause 7 can be useful to have a lower bound of ElpH,k,SD. A. Benavent-Climent 30th March 2022

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Indirect verification

- 1. The main structural system is classified as DC1 or DC2 or DC3 depending on the compliance of the conditions in 6.2.7 EN1998 1-1 and **10** to **15** in EN1998 1-2. This determines the maximum allowable q_p
- 2. Calculate the displacement ductility demand *dlroof*1 is the maximum roof displacement in the first mode in the direction considered, and Here, *dlroof*1 is obtained from the plastic energy dissipation den $d_{roofy} = \frac{T_1^2(v_{py,1}+v_{dy,1})r_1}{4\pi^2 m_{eff1}}$, $k, E_{H,k}$, assuming that $E_{H,k}$ is dissipated in one cycle of amplitude equal to the maximum interstory drift: $dlroof, 1 = \sum k = 1.1N = \{dlpy, k + ElH, k/4(Vlpy, k + Vldy, k)\}$
- 3. Check: $\mu l f \leq q l D$.

(assumes that $E_{H,k}$ is dissipated in one cycle of maximum interstory drift)



MAIN VERIFICATION on the Energy Dissipation Devices (EDDs):

The energy that the energy dissipation ≥ system at the k-th storey can dissipate before it reaches the SD limit state

The maximum energy dissipation demand on the energy dissipation system at the k-th storey under the reference seismic action

Direct verification: $E_{dH,k,SD} \ge E_{dH,k,SD}$

The energy dissipation capacity of the EDDs installed on each storey k when any EDD on the same storey attains SD limit state $E_{dH,k,SD}$ (evaluated with EN15129)

$$E_{dH,k,SD} = L_{dH,k,SD}$$

$$E_{dH,k,max} = E_{H,k} \begin{bmatrix} V_{dy,k}(d_{r,k,1}-d_{dy,k}) \\ V_{py,k}(d_{r,k,1}-d_{py,k}) + V_{dy,k}(d_{r,k,1}-d_{dy,k}) \end{bmatrix} + 40 \begin{bmatrix} V_{dy,k}[d_{py,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{py,k} + V_{dy,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{yy,k} + V_{dy,k} + V_{dy,k} + V_{dy,k} \end{bmatrix} + 100 \begin{bmatrix} V_{dy,k}[d_{D,k} - d_{dy,k}] \\ V_{yy,k} + V_{dy,k} +$$



ADDITIONAL VERIFICATION on the Main Structural System and Energy Dissipation System

- The amount of energy that the overall ≥ structure can absorb while the primary seismic members of the main structural system remain elastic
- The energy input be a low intensity earthquake, estimated as ¹/₄ of the energy input by the reference seismic action (design earthquake)





ADDITIONAL VERIFICATIONS on the Main Structural System and Auxiliary elements of Energy Dissipation System ($E_d \le R_d$)

The seismic action effects are calculated in the stage of maximum displacement:

 $E\downarrow Emax, disp = \blacksquare SRSS@CQC \{E\downarrow Emax, disp, m\}$



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Thank you for your attention

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